

$m_1 = 6 [kg]$
 $m = 3 [kg]$
 $R = 0.3 [m]$
 $v_B = 0.3 [m/s]$
 $\mu_1, \mu_0 = 30^\circ$
 $\mu_0 = 1.0$
 $\mu = 0.1$
 $g = 9.81 [m/s^2]$

- gyorsulásallapot súrlódási tényezővel, P_2, β_2
- SZTA, mozgásegyenlet
- $M = ?$, valós gördül
- M munkája, D pontban nicholas elmozdulása, függőleges allgás

Tth gördül
 1) Kinematika

$\underline{v}_A = 0, \underline{v}_B = \begin{bmatrix} v_B \\ 0 \\ 0 \end{bmatrix}, \underline{v}_C = v_C \cdot \underline{j}, \underline{\omega}_1 = \omega_1 \cdot \underline{k}, \underline{\omega}_2 = \omega_2 \cdot \underline{k}$
 $\underline{r}_{AB} = R \cdot \underline{j}$
 $\underline{v}_B = \underline{v}_A + \underline{\omega}_1 \times \underline{r}_{AB}$
 $\omega_1 = -v_B / R = -1 [rad/s]$
 $\underline{r}_{BC} = l_2 \cdot \underline{i} + R \cdot \underline{j}$
 $\underline{v}_C = \underline{v}_B + \underline{\omega}_2 \times \underline{r}_{BC}$
 $\omega_2 = \frac{v_B}{\sin \gamma (l_2 + R)}, \omega_2 v_C = v_B \frac{\cos \gamma}{\sin \gamma}$
 $\omega_2 = 0.4 [rad/s], v_C = 0.520 [m/s]$

$$\underline{a}_B = \underline{a}_A + \underline{\epsilon}_1 \times \underline{r}_{AB} - \omega_1^2 \underline{r}_{AB}; \quad \underline{\epsilon}_1 = \epsilon_1 \underline{k}, \underline{a}_A = a_A \cdot \underline{j}, \underline{a}_B = \underline{0}$$

$$\epsilon_1 = 0 \text{ [rad/s}^2\text{]}, a_A = R\omega_1^2 = 0.3 \text{ [m/s}^2\text{]}$$

$$\underline{a}_C = \underline{a}_B + \underline{\epsilon}_2 \times \underline{r}_{BC} - \omega_2^2 \underline{r}_{BC}, \quad \underline{\epsilon}_2 = \epsilon_2 \underline{k}, \underline{a}_C = a_C \cdot \underline{j}, \underline{a}_B = \underline{0}$$

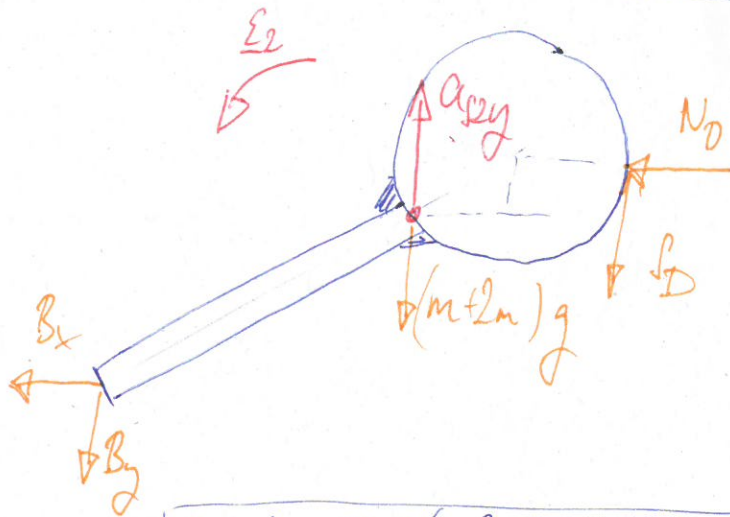
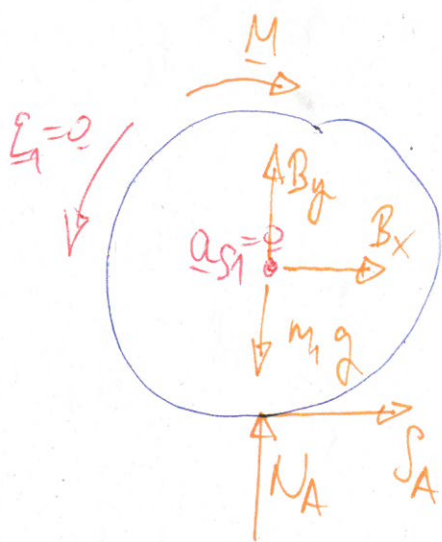
$$\epsilon_2 = -\omega_2^2 \frac{2 \cos(\varphi)}{\sin(\varphi)} = -0.277 \text{ [rad/s}^2\text{]}, \quad a_C = -\omega_2^2 (l+R) \frac{1}{\sin(\varphi)} = -0.4 \text{ [m/s}^2\text{]}$$

$$\underline{r}_{BS2} = \frac{1}{m+2m} \left(m \frac{l}{2} \begin{bmatrix} \cos \varphi \\ \sin \varphi \\ 0 \end{bmatrix} + 2m(l+R) \begin{bmatrix} \cos \varphi \\ \sin \varphi \\ 0 \end{bmatrix} \right) = 4R \begin{bmatrix} \cos \varphi \\ \sin \varphi \\ 0 \end{bmatrix}$$

$$\underline{a}_{S2} = \underline{a}_B + \underline{\epsilon}_2 \times \underline{r}_{BS2} - \omega_2^2 \underline{r}_{BS2} = \begin{bmatrix} 0 \\ a_{S2y} \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ -0.384 \\ 0 \end{bmatrix} \text{ [m/s}^2\text{]}$$

1. test $\underline{B} = \underline{I} \begin{bmatrix} 0 \\ 0 \end{bmatrix}$, 2. test $\begin{bmatrix} a_{S2y} \\ \epsilon_2 \end{bmatrix}$ P_2, G_2 ✓

SZTA'



1. test $\underline{I} = \underline{F}$

$$\begin{aligned} \rightarrow x: m_1 \cdot 0 &= S_A + B_x \\ \rightarrow y: m_1 \cdot 0 &= N_A + B_y - m_1 g \\ \dot{\Pi}_{S1} = \underline{M}_{S1} \rightarrow z: \Theta_{S1} \cdot 0 &= S_A \cdot R - M \end{aligned}$$

2. test $\underline{P} \times \underline{r} = (\underline{m} + 2\underline{m}) \underline{0} = -B_x - N_D$

$$\underline{I} = \underline{F} \rightarrow y: (m+2m) a_{S2y} = -B_y - S_D - (m+2m)g$$

$$\dot{\Pi}_{S2} = \underline{M}_{S2} \rightarrow z: \Theta_{S2} \cdot \epsilon_2 = B_y \cdot 4R \cos(\varphi) + B_x \cdot 4R \sin(\varphi) + N_D \cdot R \sin(\varphi) - S_D \cdot R (1 + \cos(\varphi))$$

$N_A, S_A, B_x, B_y, N_D, S_D, M$

$$3) \Theta_{sz} = \frac{1}{12} m l^2 + m \left(\frac{l}{2}\right)^2 + \frac{1}{2} (2m) R^2 + (2m) R^2 = 2.25 [\text{kg m}^2]$$

Sinkt ab!

$$S_D = \mu N_D$$

N_A	S_A	B_x	B_y	N_D	S_D	M		
0	1	1	0	0	0	0	N_A	0
1	0	0	1	0	0	0	S_A	$m_1 g$
0	R	0	0	0	0	-1	B_x	0
0	0	-1	0	-1	0	0	B_y	0
0	0	0	-1	0	-1	0	N_D	$3m(a_{sz} + g)$
0	0	$-4R \sin \varphi$	$4R \cos \varphi$	$R \sin \varphi$	$-R(1 + \cos \varphi)$	0	S_D	$\Theta_{sz} \epsilon_2$
0	0	0	0	μ	1	0	M	0

$$N_A = 158.5 [\text{N}], S_A = 148.4 [\text{N}], B_x = -148.4 [\text{N}], B_y = -93.67 [\text{N}], N_D = 148.4 [\text{N}]$$

$$S_D = 14.83 [\text{N}], M = 44.50 [\text{Nm}]$$

$$\frac{S_A}{N_A} = 0.94 < \mu_0 \text{ g\u00e4nstlich } \checkmark$$

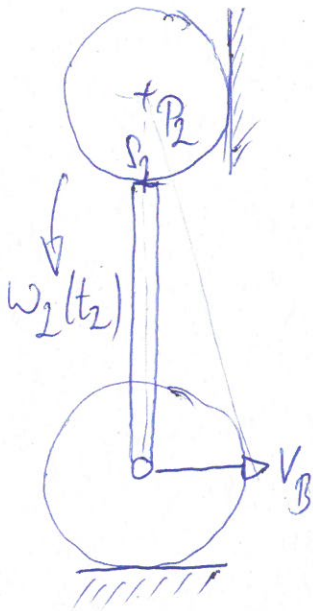
Munkafelad.

$$I_2 - I_1 = W_{12}$$

$$I_1 = \frac{1}{2} m_1 v_B^2 + \frac{1}{2} \Theta_{m1} \omega_1^2 + \frac{1}{2} 3m v_{S2}^2 + \frac{1}{2} \Theta_{m2} \omega_2^2$$

$$\underline{v_{S2}} = \underline{v_B} + \underline{\omega_2} \times \underline{r_{BS_2}} = \begin{bmatrix} 0.06 \\ 0.416 \\ 0 \end{bmatrix} \left[\frac{m}{s} \right]$$

t₂



$$\omega_2 = \frac{v_B}{4r_2} = 0.2 \left[\frac{\text{rad}}{s} \right]$$

$$v_{S2}(t_2) = 0.24 \left[\frac{m}{s} \right]$$

$$I_2 = \frac{1}{2} m_1 v_B^2 + \frac{1}{2} \Theta_{m1} \omega_1^2 + \frac{1}{2} 3m v_{S2}(t_2)^2 + \frac{1}{2} \Theta_{m2} \omega_2(t_2)^2$$

$$W_{12} = -(U_2 - U_1) + W_{12}^M = -3mg(l - l \sin \theta) + W_{12}^M$$

$$\frac{1}{2} 3m (v_{S2}(t_2)^2 - v_{S2}(t_1)^2) + \frac{1}{2} \Theta_{m2} (\omega_2(t_2)^2 - \omega_1(t_1)^2) = -3mg(l - l \sin \theta) + W_{12}^M$$

$$W_{12}^M = 53.62 \text{ [J]}$$