

$v, \omega_{10}, m, r, t, h, b$ adott, $\underline{\Theta}_S, \underline{\Pi}_S / 2, \underline{\Theta}_B, \underline{\Pi}_B / 3, T$

1) $\underline{\Theta}_S$, $y \rightarrow$ forgastengely $\Theta_{S,y} = \frac{1}{2} m r^2$

$$\underline{\Theta}_S = \begin{bmatrix} \Theta_{S,x} & 0 & 0 \\ 0 & \Theta_{S,y} & 0 \\ 0 & 0 & \Theta_{S,z} \end{bmatrix}$$

$$\Theta_{S,x} = \Theta_{S,z} = \frac{1}{4} m r^2 + \frac{1}{2} m l^2$$

$$\underline{\Pi}_S = \underline{\Theta}_S \cdot \underline{\omega}_{20}, \quad \underline{\omega}_{20} = \underline{\omega}_{10} + \underline{\omega}_{21}, \quad \underline{\omega}_{10} = \begin{bmatrix} \omega_{10} \\ 0 \\ 0 \end{bmatrix}, \quad \underline{\omega}_{21} = \begin{bmatrix} 0 \\ \omega_{21} \\ 0 \end{bmatrix}$$

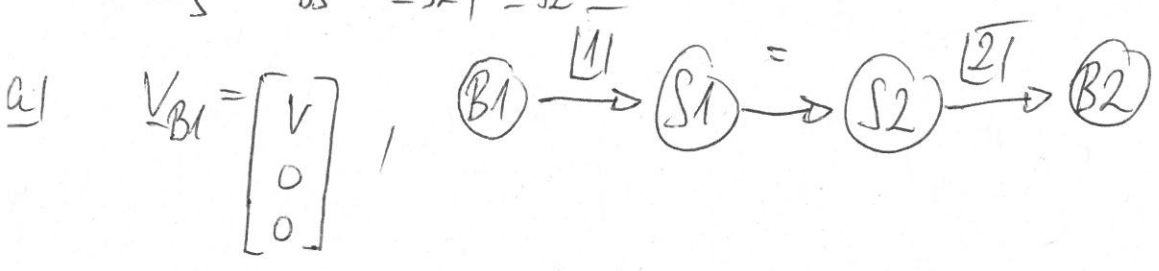
$$\omega_{21} = \frac{v}{r}, \quad \underline{\omega}_{20} = \begin{bmatrix} \omega_{10} \\ v/r \\ 0 \end{bmatrix}, \quad \underline{\Pi}_S = \underline{\Theta}_S \cdot \underline{\omega}_{20} = \begin{bmatrix} \Theta_{S,x} \cdot \omega_{10} \\ \Theta_{S,y} \cdot \frac{v}{r} \\ 0 \end{bmatrix}$$

$$2) \underline{\Theta}_B = \underline{\Theta}_S + \underline{\Theta}_{BS}, \quad \underline{\Theta}_{BS} = \left[(\underline{r}_{BS}^T \underline{r}_{BS}) \underline{I} - \underline{r}_{BS} \underline{r}_{BS}^T \right] m$$

$$\underline{r}_{BS} = \begin{bmatrix} x_{BS} \\ y_{BS} \\ z_{BS} \end{bmatrix} = \begin{bmatrix} 0 \\ t \\ -b \end{bmatrix}, \quad \underline{\Theta}_{BS} = m \begin{bmatrix} t^2 + b^2 & 0 & 0 \\ 0 & b^2 & tb \\ 0 & 0 & t^2 \end{bmatrix}, \quad \underline{\Theta}_{BS} = \underline{\Theta}_{SB}!$$

$$\underline{\Pi}_B = \underline{\Theta}_B \cdot \underline{\omega}_0 + \underline{r}_{BS} \times (m \underline{v}_{B2})$$

$$\underline{\Pi}_B = \underline{\Pi}_S + \underline{r}_{BS} \times \underline{I}_{S2}, \quad \underline{I}_{S2} = m \underline{v}_{S2}$$



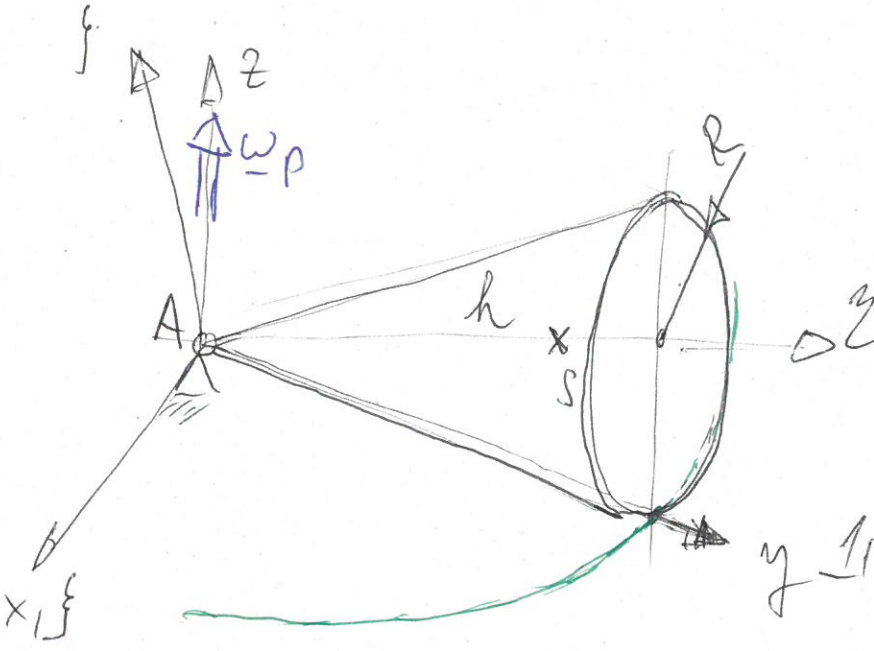
HT...

$$b) \text{ Das } \underline{v}_{S1} = \underline{v}_{B1} + \underline{\omega}_0 \times \underline{r}_{BS} = \begin{bmatrix} v \\ \omega_0 b \\ \omega_0 t \end{bmatrix}, \quad \underline{v}_{S1} = \underline{v}_{S2}$$

$$\underline{r}_{BS} \times (m \underline{v}_{B2}) = m \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ 0 & + & -b \\ v & \omega_0 b & \omega_0 t \end{vmatrix} = m \begin{bmatrix} \omega_0 (t^2 + b^2) \\ -bv \\ -tv \end{bmatrix}$$

$$\underline{\Pi}_B = \begin{bmatrix} \Theta_{Sx} \omega_0 + m(t^2 + b^2) \\ v(\Theta_{Sy} / r - mb) \\ -m tv \end{bmatrix}$$

$$T = \frac{1}{2} m v_S^2 + \frac{1}{2} \underline{\omega}_0^T \underline{\Pi}_S \underline{\omega}_0 = \frac{1}{2} m (v^2 + \omega_0^2 (b^2 + t^2)) + \frac{1}{2} (\Theta_{Sx} \omega_0^2 + \Theta_{Sy} \frac{v^2}{r^2})$$



$$m = 6 \text{ [kg]}$$

$$R = 0.2 \text{ [m]}$$

$$h = 0.3 \text{ [m]}$$

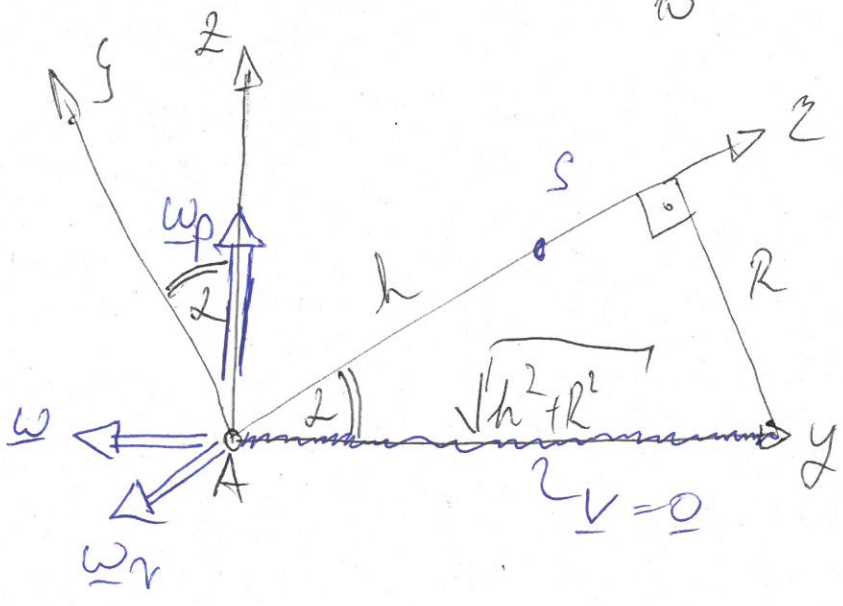
$$\omega_p = 2 \text{ [rad/s]}$$

$y \perp \underline{v} = ?$, $2 \perp \underline{v}_S$, $3 \perp \underline{v}_A$

$$T = \frac{1}{2} m v_s^2 + \frac{1}{2} \underline{\omega}^T \underline{\Theta}_S \underline{\omega} = \frac{1}{2} \underline{\omega}^T \underline{\Theta}_A \underline{\omega} \quad \text{All's points!}$$

$$\underline{\Theta}_A = \begin{bmatrix} \Theta_x & 0 & 0 \\ 0 & \Theta_y & 0 \\ 0 & 0 & \Theta_z \end{bmatrix}, \quad \Theta_x = \Theta_y = \frac{3}{10} m (4R^2 + h^2) + m \left(\frac{3}{4}h\right)^2$$

$$\Theta_z = \frac{3}{10} m R^2 \quad \boxed{\Theta_x = \Theta_y = \frac{3}{20} (4h^2 + R^2) m}$$



$$\underline{\omega}_p = \begin{bmatrix} 0 \\ \omega_p \sin \alpha \\ \omega_p \cos \alpha \end{bmatrix}$$

$$\underline{\omega}_r = \begin{bmatrix} 0 \\ -\omega_r \\ 0 \end{bmatrix}, \quad \underline{\omega} = \begin{bmatrix} 0 \\ -\omega \cos \alpha \\ \omega \sin \alpha \end{bmatrix}, \quad \underline{\omega} = \underline{\omega}_r + \underline{\omega}_p$$

$$\left\{ \begin{aligned} \omega &= \omega_p \frac{\omega s d}{\delta h d} = \omega_p \frac{h}{R} & \Rightarrow \underline{\omega} &= \omega_p \frac{h}{R \sqrt{R^2 + h^2}} \begin{bmatrix} -\Theta_z \\ -h \cdot \omega_z \\ R \cdot \omega_y \end{bmatrix} \\ & & (5.2.5) & \end{aligned} \right.$$

$$T = \frac{1}{2} \underline{\omega}^T \underline{\Theta}_A \underline{\omega} = \frac{1}{2} (\Theta_z \omega_z^2 + \Theta_y \omega_y^2) = \cancel{2.35} [J] = 0.723 [J]$$

$$3) \quad \underline{T}_A = \underline{\Theta}_A \underline{\omega} + r_{AS} \times (m \underline{v}_A) = \underline{\Theta}_A \underline{\omega} = \begin{bmatrix} 0 \\ \Theta_z \omega_z \\ \Theta_y \omega_y \end{bmatrix} = \begin{bmatrix} 0 \\ -0.1737 \\ 0.5990 \end{bmatrix} \left[\frac{\text{kgm}^2}{s} \right]$$

$$[\underline{\Theta}_A] = 1 \text{ kgm}^2$$

$$2) \quad \underline{T}_S = \underline{\Theta}_S \cdot \underline{\omega}, \quad \underline{\Theta}_A = \underline{\Theta}_S + \underline{\Theta}_{AS}, \quad r_{AS} = \begin{bmatrix} 0 \\ \frac{3}{4} h \\ 0 \\ -\underline{\Theta}_{AS} \end{bmatrix}$$

$$\underline{\Theta}_{AS} = m \left(\frac{3}{4} h \right)^2 \begin{bmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix} \rightsquigarrow \underline{\Theta}_S = \underline{\Theta}_A - \underline{\Theta}_{AS}$$

$$\underline{T}_S = \begin{bmatrix} 0 \\ -0.1737 \\ 0.0936 \end{bmatrix} \left[\text{kgm}^2/s \right]$$